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Non-equilibrium dynamics of disordered systems: understanding the broad continuum of relevant time scales via a strong-disorder RG in configuration space

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Abstract

We show that an appropriate description of the non-equilibrium dynamics of disordered systems is obtained through a strong disorder renormalization procedure in *configuration space* that we define for any master equation with transitions rates $W(\mathcal{C} \rightarrow \mathcal{C}')$ between configurations. The idea is to eliminate iteratively the configuration with the highest exit rate $W_{\text{out}}(\mathcal{C}) = \sum_{\mathcal{C}'} W(\mathcal{C} \rightarrow \mathcal{C}')$ to obtain renormalized transition rates between the remaining configurations. The multiplicative structure of the new generated transition rates suggests that for a very broad class of disordered systems, the distribution of renormalized exit barriers defined as $B_{\text{out}}(\mathcal{C}) \equiv -\ln W_{\text{out}}(\mathcal{C})$ will become broader and broader upon iteration, so that the strong disorder renormalization procedure should become asymptotically exact at large time scales. We have checked numerically this scenario for the non-equilibrium dynamics of a directed polymer in a two-dimensional random medium.

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(Some figures in this article are in colour only in the electronic version)

The non-equilibrium dynamics of disordered systems usually displays a broad continuum of relevant time scales, that give rise to a lot of striking properties such as ageing, rejuvenation and memory that have been studied a lot both experimentally and theoretically (see [1] and references therein). In finite dimensions, these effects can be understood via the growth of some coherence length $l(t)$ that separates the smaller lengths $l < l(t)$ which are quasi-equilibrated from the bigger lengths $l > l(t)$ which are completely out of equilibrium. The slow nature of the dynamics then reflects the fact that equilibration on larger length scales requires to overcome larger and larger barriers. Within the droplet scaling theory proposed both for spin-glasses [2, 3] and for the directed polymer in a random medium [4], the non-equilibrium dynamics is activated with barriers scaling as power law $B(l) \sim l^\psi$ of the length scale l . The typical time associated to scale l then grows as an exponential

In $t_{\text{typ}}(l) \sim B(l) \sim l^\psi$, or equivalently, the characteristic length scale $l(t)$ associated with time t grows only logarithmically $l(t) \sim (\ln t)^{1/\psi}$. In numerical studies, this logarithmic behavior has remained controversial because the maximal equilibrated length l_{max} measured at the end of the simulations is usually rather small, so that many fits of the data are possible. For instance, in Monte Carlo simulations of 2D or 3D random ferromagnets [5] or spin-glasses [6], the maximal equilibrated size is usually only of order $l_{\text{max}} \sim 10$. A noteworthy exception is the simulation of an elastic line in a random medium where sizes of order $l_{\text{max}} \sim 100$ have been measured [7] with the conclusion that the length $l(t)$ grows logarithmically with a barrier exponent $\psi \sim 0.49$ (whereas power-law fits $l(t) \sim t^{1/z}$ are excluded at large times). Note that the difficulties met in dynamical Monte Carlo simulations of disordered systems come precisely from the presence of a continuum of relevant time scales ranging from the microscopic scale of single moves to the equilibrium time of the full system. Then even faster-than-the-clock Monte Carlo algorithms [8], where each iteration leads to a movement, become inefficient because they face the 'futility' problem [9]: the number of different configurations visited during the simulation remains very small with respect to the accepted moves. The reason is that the system visits over and over again the same configurations within a given valley before it is able to escape toward another valley where it will be trapped even longer!

In this paper, we argue that the appropriate description of these dynamics with a broad continuum of relevant time scales requires some renormalization where the smaller time scales are successively integrated out to obtain the properties of the large-time dynamics. Moreover, since we expect that in these systems, disorder dominates over thermal fluctuations at large scales, the most appropriate renormalization scheme is a so-called strong disorder renormalization (RG) procedure (see [10] for a review). This very specific type of RG, which was introduced by Ma and Dasgupta [11] and developed by Fisher [12] in the field of quantum-spin chains, has been then successfully applied to various classical disordered dynamical models, such as random walks in random media [13], reaction diffusion in a random medium [14], coarsening dynamics of classical spin chains [15], trap models [16], absorbing state phase transitions [17], zero range processes [18], exclusion processes [19]. In all these cases, the strong disorder RG rules have been formulated *in real space*, with specific rules depending on the problem. In this paper, we show that for more complex systems where the formulation of strong disorder RG rules has not been possible in real space, it is nevertheless possible to formulate strong disorder RG rules *in configuration space*. Moreover, this formulation in configuration space is very general since it can be defined for any master equation describing the evolution of the probability $P_t(\mathcal{C})$ to be in configuration \mathcal{C} at time t ,

$$\frac{dP_t(\mathcal{C})}{dt} = \sum_{\mathcal{C}'} P_t(\mathcal{C}') W(\mathcal{C}' \rightarrow \mathcal{C}) - P_t(\mathcal{C}) W_{\text{out}}(\mathcal{C}). \quad (1)$$

The notation $W(\mathcal{C}' \rightarrow \mathcal{C})$ represents the transition rate per unit time from configuration \mathcal{C}' to \mathcal{C} , and

$$W_{\text{out}}(\mathcal{C}) \equiv \sum_{\mathcal{C}'} W(\mathcal{C} \rightarrow \mathcal{C}') \quad (2)$$

represents the total exit rate out of configuration \mathcal{C} . The two important properties of this master equation are the following: (i) the exit time τ from configuration \mathcal{C} is distributed with the exponential law $P_{\mathcal{C}}^{\text{exit}}(\tau) = W_{\text{out}}(\mathcal{C}) e^{-\tau W_{\text{out}}(\mathcal{C})}$; (ii) the new configuration \mathcal{C}' where the jumps at time τ when it leaves the configuration \mathcal{C} is chosen with the probability $\pi_{\mathcal{C}}(\mathcal{C}') = \frac{W(\mathcal{C} \rightarrow \mathcal{C}')}{W_{\text{out}}(\mathcal{C})}$.

For dynamical models, the aim of any renormalization procedure is to integrate over 'fast' processes to obtain effective properties of 'slow' processes. The general idea of 'strong renormalization' consists of eliminating iteratively the 'fastest' process. For the master

equation of equation (1), we thus define the strong disorder renormalization in configuration space by the iterative elimination of the configuration with the highest exit rate (equation (2)). Let us call this configuration \mathcal{C}^* , and its exit rate W_{out}^*

$$W_{\text{out}}^* = W_{\text{out}}(\mathcal{C}^*) \equiv \max_{\mathcal{C}}[W_{\text{out}}(\mathcal{C})]. \quad (3)$$

We now have to compute the ‘new’ effective transitions rates $W^{\text{new}}(\mathcal{C} \rightarrow \mathcal{C}')$ among the remaining configurations in terms of the ‘old’ transitions rates $W^{\text{old}}(\mathcal{C} \rightarrow \mathcal{C}')$ where the decimated configuration \mathcal{C}^* was still present. The only changes occur for the configurations called here $(\mathcal{C}_1, \mathcal{C}_2, \dots, \mathcal{C}_n)$ that were related via positive rates $W^{\text{old}}(\mathcal{C}^* \rightarrow \mathcal{C}_i) > 0$ and $W^{\text{old}}(\mathcal{C}_i \rightarrow \mathcal{C}^*) > 0$ to the decimated configuration \mathcal{C}^* (here we will assume, for the simplicity of the discussion, and because it is usually the case in statistical physics models, that if a transition has a strictly positive rate, the reverse transition has also a strictly positive rate; but of course the renormalization rules can be simply extended to other cases). The $2n$ rates $W^{\text{old}}(\mathcal{C}^* \rightarrow \mathcal{C}_i)$ and $W^{\text{old}}(\mathcal{C}_i \rightarrow \mathcal{C}^*)$ with $i = 1, \dots, n$ have to be eliminated, after taking into account their effects on transitions between pairs of neighbors of \mathcal{C}^* . For each neighbor configuration \mathcal{C}_i with $i \in (1, \dots, n)$, the renormalized rate to go to the configuration \mathcal{C}_j with $j \in (1, \dots, n)$ and $j \neq i$ reads

$$W^{\text{new}}(\mathcal{C}_i \rightarrow \mathcal{C}_j) = W^{\text{old}}(\mathcal{C}_i \rightarrow \mathcal{C}_j) + W^{\text{old}}(\mathcal{C}_i \rightarrow \mathcal{C}^*) \times \frac{W^{\text{old}}(\mathcal{C}^* \rightarrow \mathcal{C}_j)}{W_{\text{out}}^*}. \quad (4)$$

The first term represents the ‘old’ transition rate (possibly zero), whereas the second term represents the transition via the decimated configuration \mathcal{C}^* : the factor $W^{\text{old}}(\mathcal{C}_i \rightarrow \mathcal{C}^*)$ takes into account the transition rate to \mathcal{C}^* , whereas the second factor represents the probability to make a transition toward \mathcal{C}_j when in \mathcal{C}^* . Note that the rule of equation (4) has been recently proposed in [20] to eliminate ‘fast states’ from various dynamical problems with two very separated time scales. The physical interpretation of this rule is as follows: the time spent in the decimated configuration \mathcal{C}^* is neglected with respect to the other time scales remaining in the system. The validity of this approximation within the present renormalization procedure will be discussed in detail below. To finish the decimation of \mathcal{C}^* , we have now to update the exit rates out of the neighboring configurations \mathcal{C}_i

$$W_{\text{out}}^{\text{new}}(\mathcal{C}_i) = \sum_{\mathcal{C}} W^{\text{new}}(\mathcal{C}_i \rightarrow \mathcal{C}). \quad (5)$$

Since the only changes come from the rate toward \mathcal{C}^* that has disappeared and from the rates toward $j \in (1, \dots, n)$ with $j \neq i$ that have changed according to equation (4), one obtains

$$W_{\text{out}}^{\text{new}}(\mathcal{C}_i) = W_{\text{out}}^{\text{old}}(\mathcal{C}_i) - W^{\text{old}}(\mathcal{C}_i \rightarrow \mathcal{C}^*) \frac{W^{\text{old}}(\mathcal{C}^* \rightarrow \mathcal{C}_i)}{W_{\text{out}}^*}.$$

The physical meaning of this rule is the following. The exit rate out of the configuration \mathcal{C}_i decays because the previous transition toward \mathcal{C}^* could lead to an immediate return toward \mathcal{C}_i with probability $\frac{W^{\text{old}}(\mathcal{C}^* \rightarrow \mathcal{C}_i)}{W_{\text{out}}^*}$. After the decimation of the configuration \mathcal{C}^* , this process is not considered as an ‘exit’ process anymore, but as a residence process in the configuration \mathcal{C}_i . This point is very important to understand the meaning of the RG procedure: the remaining configurations at a given stage are ‘formally’ microscopic configurations of the initial master equation, but each of these remaining microscopic configuration actually represents some ‘valley’ in configuration space that takes into account all the previously decimated configurations. Note that in practice, the renormalized rates $W(\mathcal{C} \rightarrow \mathcal{C}')$ can rapidly become very small as a consequence of the multiplicative structure of the renormalization rule of equation (4). So the appropriate variables are the logarithms of the transition rates, called ‘barriers’ from now on. The barrier $B(\mathcal{C} \rightarrow \mathcal{C}')$ from \mathcal{C} to \mathcal{C}' is defined by

$B(\mathcal{C} \rightarrow \mathcal{C}') \equiv -\ln W(\mathcal{C} \rightarrow \mathcal{C}')$ and similarly the exit barrier out of configuration \mathcal{C} is defined by

$$B_{\text{out}}(\mathcal{C}) \equiv -\ln W_{\text{out}}(\mathcal{C}). \quad (6)$$

As mentioned above, the approximation made in the renormalization rule of equation (4) consists of neglecting the time spent in the decimated configuration \mathcal{C}^* with respect to the other time scales remaining in the system. In our present framework, this means that the maximal exit rate chosen in equation (3) should be well separated from the exit rates of the neighboring configurations \mathcal{C}_i . The crucial idea of ‘infinite disorder fixed point’ [12, 10] is that even if this approximation is not perfect during the first steps of the renormalization, this approximation will become better and better at large RG scale if the probability distribution of the remaining exit rates becomes broader and broader upon iteration. More precisely, if the renormalization scale Γ is defined as the exit barrier of the last eliminated configuration $\Gamma = B_{\text{out}}(\mathcal{C}^*)$, one expects that the probability distribution of the remaining exit barriers $B_{\text{out}} \geq \Gamma$ will converge toward some scaling form

$$P_{\Gamma}(B_{\text{out}} - \Gamma) \underset{\Gamma \rightarrow \infty}{\simeq} \frac{1}{\sigma(\Gamma)} \tilde{P} \left(\frac{B_{\text{out}} - \Gamma}{\sigma(\Gamma)} \right), \quad (7)$$

where \tilde{P} is the fixed point probability distribution, and where $\sigma(\Gamma)$ is the appropriate scaling factor. The notion of ‘infinite disorder fixed point’ means that the width $\sigma(\Gamma)$ grows to infinity with the RG scale Γ . For instance, in previously known cases of infinite disorder fixed points where calculations can be done explicitly [10], the scale $\sigma(\Gamma)$ grows linearly $\sigma(\Gamma) \sim \Gamma$, and the fixed point distribution is an exponential $\tilde{P}(x) = e^{-x}$. Whenever the flow is toward an ‘infinite disorder fixed point’, the strong disorder renormalization procedure becomes asymptotically exact at large RG scales. For our present problem, the convergence toward an ‘infinite disorder fixed point’ will depend on the initial condition of the transition rates, i.e. on the model (and on the temperature if there are phase transitions). However, the form of the renormalization rule of equation (4) is sufficiently similar to the usual Ma-Dasgupta rules [10] to think that the convergence toward some infinite disorder fixed point should be realized in a very broad class of disordered systems in their glassy phase. In practice, it can be checked numerically for each model of interest.

As an example of application, we consider the directed polymer in a two-dimensional random medium, a model first introduced to describe interfaces in random ferromagnets [23] (see [24] for a review). The statics is well described by the Fisher–Huse droplet theory [4] as checked by detailed numerical studies [4, 25]. We use the following discrete formulation for a polymer of length L attached at the origin: the 2^L configurations (h_1, \dots, h_L) correspond to the random walks $h_x - h_{x-1} = \pm 1$ starting at $h_0 = 0$. The energy of a configuration is $E = \sum_{x=1}^L \epsilon(x, h_x)$ where the site random energies $\epsilon(x, h)$ are Gaussian $\rho(\epsilon) = e^{-\epsilon^2/2}/\sqrt{2\pi}$. We consider the usual Metropolis dynamics at temperature $T = 0.5$ defined by the transition rates

$$W(\mathcal{C} \rightarrow \mathcal{C}') = \delta_{(\mathcal{C}, \mathcal{C}')} \frac{1}{L} \min(1, e^{-(E(\mathcal{C}') - E(\mathcal{C}))/T}),$$

where the factor $\delta_{(\mathcal{C}, \mathcal{C}')}$ means that the two configurations are related via the move of a single monomer $h_x \rightarrow h_x \pm 2$. So initially each configuration has at most L neighbors corresponding to single moves. However during the renormalization, many new transition rates will be generated via equation (4), as in real-space strong disorder RG studies of quantum models in dimension $d > 1$ [21, 22]. Here, to validate our approach, we have decided to follow exactly the full RG flow, without disregarding any new transition rate. As a consequence, we have been able to study numerically only moderate lengths $L \leq 9$ ($2^L \leq 512$ configurations) with a

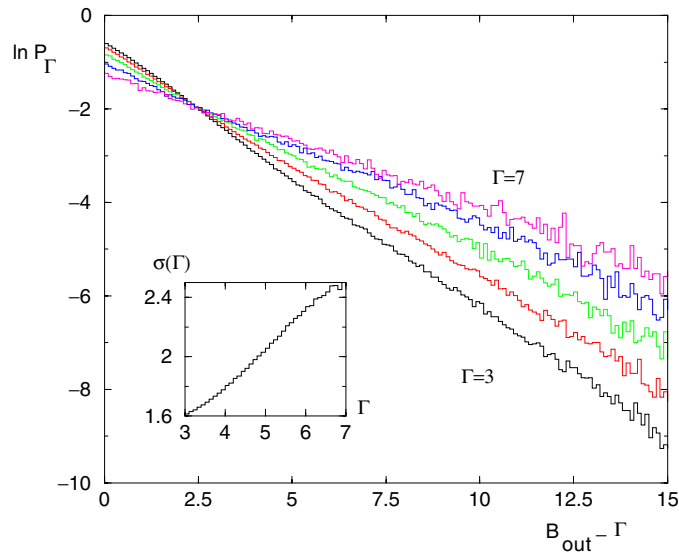


Figure 1. Flow of the probability distribution $P_\Gamma(B_{out} - \Gamma)$ of the renormalized exit barriers (see equation (7)) as the RG scale grows $\Gamma = 3, 4, 5, 6, 7$. Inset: growth of the width $\sigma(\Gamma)$ with the RG scale Γ . (Data obtained for a directed polymer of length $L = 9$ in a two-dimensional random medium with $2^L = 512$ configurations, the statistics is over $n_s = 15 \cdot 10^4$ disordered samples.)

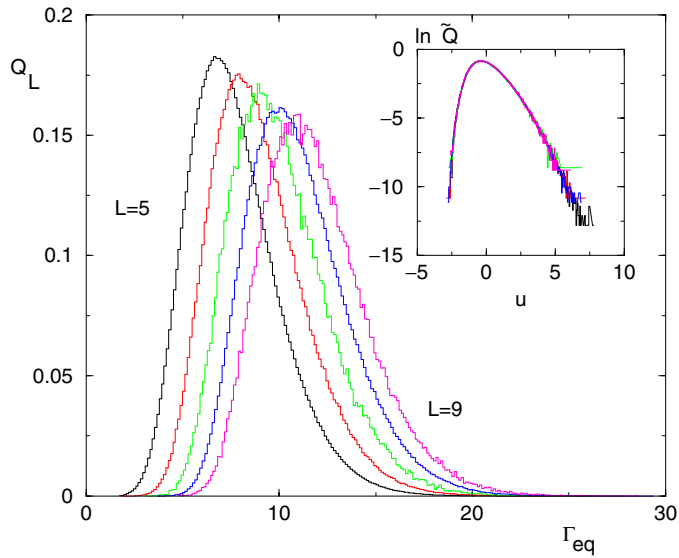


Figure 2. Statistics of the equilibrium time over the samples for a directed polymer in a two-dimensional random medium: probability distribution $Q_L(\Gamma_{eq} = \ln t_{eq})$ for length $L = 5, 6, 7, 8, 9$ (see equation (8)). Inset: rescaled distribution $\tilde{Q}(u)$ in log representation to see the tails.

sufficient statistics of $n_s \geq 10^5$ disordered samples (we have data up to $L = 11$ with $n_s = 500$ samples, but histograms are too noisy).

We find (see figure 1) that the probability distribution of renormalized exit barrier of equation (7) flows toward an ‘infinite disorder’ fixed point, with a width growing as $\sigma(\Gamma) \sim \Gamma$ and a rescaled probability which is extremely close to the exponential $\tilde{P}(x) \sim e^{-x}$. Note that this type of renormalized distribution seems extremely robust within strong disorder RG since they hold for exactly in soluble models in $d = 1$ [10] and have also been found numerically in quantum models in dimension $d > 1$ [21]. In a finite sample, the typical equilibrium time t_{eq} can be obtained from the last decimated barrier Γ_{eq} leading to a single surviving configuration via $\Gamma_{\text{eq}} = \ln t_{\text{eq}}$. Its probability distribution $Q_L(\Gamma_{\text{eq}} = \ln t_{\text{eq}})$ over the disordered samples of size L is shown in figure 2 for various L . The convergence toward a fixed rescaled distribution

$$Q_L(\Gamma_{\text{eq}}) \sim \frac{1}{\Delta(L)} \tilde{Q} \left(u \equiv \frac{\Gamma_{\text{eq}} - \overline{\Gamma_{\text{eq}}(L)}}{\Delta(L)} \right) \quad (8)$$

is rapid (see inset of figure 2) but the sizes studied are not sufficient to obtain, via the average $\overline{\Gamma_{\text{eq}}(L)} \sim L^\psi$ or the width $\Delta(L) \sim L^\psi$, a reliable measure of the asymptotic barrier exponent ψ , whose value has remained controversial (see [26] for a recent summary). We hope in the future to propose simplified ways of following the important rates of the renormalized flow to reach bigger system sizes [27]. We also intend to study other properties of the RG flow, in particular the structure of the evolving set of remaining configurations that label the metastable valleys above a given life-time, as well as ageing properties.

In conclusion, we have proposed to describe the non-equilibrium dynamics of disordered systems via a strong disorder renormalization procedure in *configuration space*, that we have defined for any master equation. We have argued that for a very broad class of disordered systems, the distribution of renormalized exit barriers should become broader and broader upon iteration, so that the strong disorder renormalization procedure should become asymptotically exact at large time scales. We have checked here this scenario numerically for the non-equilibrium relaxation dynamics of the directed polymer in a two-dimensional medium (see [27] for much more detailed numerical results). In the future, we intend to apply the same approach to study the driven dynamics of the directed polymer [28] as well as other disordered models [29].

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Corrigendum

Non equilibrium dynamics of disordered systems: understanding the broad continuum of relevant time scales via a strong-disorder RG in configuration space

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The last equation on page 4 should read

$$W(c \rightarrow c') = \delta_{\langle c, c' \rangle} \min\left(1, e^{-(E(c') - E(c))/T}\right).$$